

TITLE OF THE INVENTION

***FLEXIBLE APPROACH FOR REPRESENTING DIFFERENT BUS  
PROTOCOLS***

5 CROSS-REFERENCES TO RELATED APPLICATIONS: This patent application  
claims priority to provisional patent application number 60/400140, filed August 1, 2002.

STATEMENT REGARDING FEDERALLY SPONSORED RESEARCH OR  
DEVELOPMENT: Not Applicable.

10 Reference to Microfiche Appendix: Not Applicable

BACKGROUND OF THE INVENTION

FIELD OF THE INVENTION

15 This invention relates generally to electronic communications, and, more  
particularly, to data constructs for representing and manipulating communication  
protocols.

DESCRIPTION OF RELATED ART

20 A universal bus test instrument has recently been developed for exercising a wide  
variety of serial busses that operate with different interface specifications and protocols.  
U.S. Patent Application Number 10/325,070, entitled "Universal Approach for  
Simulating, Emulating, and Testing a Variety of Serial Bus Types," describes certain  
aspects of this instrument, and is herein incorporated by reference. The incorporated  
25 application and the instant application are both based on provisional applications that  
were filed on the same day. Neither application is prior art to the other.

The incorporated patent application defines the protocol and behavior of a generic  
serial bus through the use of a "bus model." As described, the bus model breaks down a  
serial bus protocol into separate generic layers that are common to all busses. For any  
30 particular target bus, the bus model expresses the target bus protocol in terms of the  
generic layers, and assigns bus-specific attributes to each generic layer. The bus model

thus forms an abstract representation of the target bus protocol in terms of the generic layers.

Fig. 1 shows a block diagram of the bus model 100. The layers of the bus model include, for example, frames (112/132), messages (114/134), words (116/136), fields  
5 (118/138), symbols (120/140), sequences (122/142), encoding (124/144), and timing (126/146).

Prior bus test instruments have been primarily bus-specific. Instruments have been designed for exercising one or more particular types of busses but were not usable for exercising other types of busses. Consequently, the communication constructs that  
10 these instruments used included only the structures needed for communicating with the specifically supported bus. They were not adaptable for other types of busses.

Fig. 2 shows a typical communication construct used by a bus-specific test instrument of the prior art. For illustrative purposes, a communication construct for a MIL-STD-1553 bus test instrument is shown. The instrument supports a set of bus-  
15 specific message types 210. The message types 210 prescribe high level operations that can be conducted on the target bus. For the 1553 bus, these message types include, among others, a Bus Controller to Remote Terminal message type (BC-RT), a Remote Terminal to Bus Controller message type (RT-BC), and a Remote Terminal to Remote Terminal message type (RT-RT).

Each of the message types 210 consists of words. In general, the target bus  
20 specification prescribes a set of word types for performing various bus operations. For the 1553 bus, three distinct word types 212 are provided: Command Word, Data Word, and Status Word.

Words consist of fields. The identities and locations of fields within words are  
25 fixed by the definition of the target bus. As shown in Fig. 2, a 1553 Command Word 216 consists of six fields 214. These fields include, as defined by the 1553 standard, Sync, RT Address, Transmit/Receive, SubAddress Mode, Data Word Count / Mode Count, and Parity.

The bus-specific constructs of the prior art each support message types and word  
30 types needed for exercising a particular target bus. They are generally limited, however, to the protocols of the respective target busses. They do not provide users with a way of defining different sets of message types or word types for different types of busses. What is needed is a more flexible way of defining bus communication.

## BRIEF SUMMARY OF THE INVENTION

5 With the foregoing background in mind, it is an object of the invention to allow users to flexibly define communication constructs for interacting with target busses or other communication media.

10 To achieve the foregoing object, as well as other objectives and advantages, a method for flexibly defining communication constructs includes providing at least one communication element type for at least one layer of a generalized communication model, such as a bus model. Each communication element type has a user-definable structure that is adaptable for representing a corresponding protocol layer of a target communication medium. Users can define specific communication element types to substantially represent the target protocol. Users can also define the communication element types to depart from the target protocol in precisely defined ways.

## BRIEF DESCRIPTION OF THE DRAWINGS

Additional objects, advantages, and novel features of the invention will become apparent from a consideration of the ensuing description and drawings, in which—

5           Fig. 1 is a conceptual block diagram of a generic bus model;

          Fig. 2 is a diagram illustrating portions of the communication construct of the MIL-STD-1553 bus according to the prior art;

          Fig. 3 is a diagram illustrating portions of a flexible communication construct according to the invention; and

10          Fig. 4 is a flowchart of a process according to the invention for defining certain data types for bus communication within a bus model.

## DETAILED DESCRIPTION OF THE PREFERRED EMBODIMENT

The generic communication construct according to the invention departs from bus-specific constructs of the prior art by allowing users to define communication  
5 element types of their own choosing. The communication element types represent different layers of the bus model. These communication element types include, for example, message types, word types, and field types. Other communication element types can be created as well to represent other layers of the bus model. Users can define these communication element types for existing busses or for future busses.

10 Fig. 3 shows an embodiment of a generic communication construct according to the invention. Like the prior art, the construct of Fig. 3 includes message types (e.g., message types 310), word types (e.g., word types 312), and field types (e.g., field types 314). Each message type includes at least one word type, and each word type includes at least one field type.

15 The construct of Fig. 3 differs markedly from the prior art, however, in its degree of flexibility. Of particular significance in attaining this flexibility is the bus model 300. As indicated above, the bus model is a generic layered structure for representing any serial bus specification. Different instances of the bus model can be created for communicating with different bus types. Each bus model instance defines  
20 communication element types that are tailored to a particular type of bus.

The bus model 300, or any instance thereof, includes a set of message types 310. Unlike the message types of the prior art, which had fixed definitions, the message types 310 have user-definable structures. For each message type, users can define a name and an ordered group of word types that constitute some meaningful communication over the  
25 target bus. For example, a user might create a Message Type N (316) consisting of word types A, B, and C. Word Types A, B, and C can be any of the word types (1 through M) defined in the bus model, and the sequence of Word Types A, B, and C performs some useful function. Users can define as many message types as they wish.

The message types for a bus may typically correspond to the messages defined by  
30 the protocol of the bus, i.e., the bus type's standard message types. However, message types can have broader applications. Users can develop custom message types to manage specific testing scenarios. Therefore, although message types are generally consistent with the target bus protocol, but they need not be limited to the specific messages that the protocol defines.

User-defined message types may also be structured differently from the message types defined in the protocol of the target bus. For instance, the protocol might define a complex message, which is more easily expressed in the bus model as a sequence of simpler or different messages. Therefore, there is no need for a direct one-to-one relationship between the messages defined in the bus protocol and those found in the bus model.

The bus model 300 includes a set of user-defined word types 312. Each word type is defined by a name and a group of field types. For example, Word Type C (part of Message Type N) may be defined to include Field Types A, B, C, and D. Users can define as many word types as they wish.

Field types are also included in the bus model 300. Field types define more concrete aspects of bus communication than message types or word types. We have found that field types are used for only a limited number of purposes. For simplicity, it is not necessary to provide users with infinite flexibility in defining the characteristics of field types. Instead, users define field type characteristics by assigning a field designation. In the preferred embodiment, users may assign each field types one of the following field designations:

Field Designation	Description
User-specified data	The user specifies the value for these fields during the test definition time or at runtime. Examples of such fields include address, subaddress (e.g., for 1553 command words), as well as the data portion (e.g., for a 1553 data word).
Constant data	The user specifies the value for these fields when defining the bus model. Like user-specified data fields, these fields are considered to be a part of the “value” of the word, or the data carried by the word, but the user cannot change them either at test definition time or at runtime. Examples of such fields include the transmit/receive bit in 1553 command words, or the subaddress/mode code field (which is fixed to be all ones or all zeros) for the 1553 mode code command words.

<b>Field Designation</b>	<b>Description</b>
Special symbol	These fields are included in the word, but are not considered to be part of the word payload. They are generally not 1's or 0's, but rather some unusual level or condition. For example, this could be a 1553 command or data sync. The user specifies the value for these fields during bus model definition, and cannot change this value either at test definition time or at runtime.
Constant non-data	These fields are included in the word, but are not considered to be part of the word payload. These fields are similar to special symbol fields in their intention, but their value can consist of regular symbols (like 1 and 0), not just the special ones. Examples include start bits and stop bits.
Parity	This one-bit field designation represents parity. Parity can be either odd or even. Parity is not considered to be part of the data portion of the word. Parity is preferably calculated (on the transmit end) and verified (on the receive end) at runtime.
CRC	This field designation represents cyclic redundancy checking. Users can specify the CRC polynomial. CRC is not considered to be part of the data portion of the word. CRC is preferably calculated (on the transmit end) and verified (on the receive end) at runtime.

Table 1. Field Designations

It is apparent from Table 1 that some field types have fixed values, such as those designated as Constant Data, whereas others have variable values, such as those designated as Parity or CRC. The specific value of a fixed field is preferably specified in the respective bus model (see "Value" setting in Table 2 below).

Field types, word types, and message types essentially form distinct structures that can be combined to build up higher level structures. For instance, the same field types can be used in different combinations to build different word types, and the same word types can be used in different combinations to build different message types. Even message types can be combined to form higher level constructs (e.g., transactions such as 1553 command-response transactions).

Definitions of the communication element types may be implemented in numerous ways. For example, they may be implemented in a single computer file, in different computer files, in hardware, or in any combination of these. In the preferred embodiment, the communication element types are provided in the form of bus files in XML format. The bus file identifies communication element types with “tags.” For example, a different tag is used for each field type, for each word type, and for each message type. The following code section shows is a generalized example of field type definitions in a bus file:

```

10      <Fields [fields attributes]>
          <Field Name = “Field 1” [field type settings] />
          <Field Name = “Field 2” [field type settings] />
          ...
          <Field Name = “Field L” [field type settings] />
15      </Fields>

```

Within any bus file, word types are also represented using XML tags. Bus files preferably define word types using the following format:

```

20      <Words [Words attributes]>
          <Word Name = “Word 1” />
          <Word Name = “Word 2” />
          ...
          <Word Name = “Word M” />
25      </Words>

```

Each word type consists of a group of field types. As is known, XML supports hierarchical arrangements of tags, wherein certain tags may be subordinate to other tags. Accordingly, subordinate tags may be used to indicate the field types that “belong to” a specific word type. For example, a bus file may represent the field types that constitute a user-defined word type, “UserWord,” as follows:

```

      <Word Name = “UserWord” >
          <WordField FieldName = “Field Type A” />
          <WordField FieldName = “Field Type B” />
          <WordField FieldName = “Field Type C” />
35      </Word>

```



Field types A, B, and C are the field types, preferably defined elsewhere in the bus file, that constitute the “UserWord” word type.

Bus files also use tags to represent message types. Message types may be represented as follows:

```
5      <Messages>

        <Message Name = “Message Type 1” [message type settings] />
        <Message Name = “Message Type 2” [message type settings] />
        ...
10     <Message Name = “Message Type N” [message type settings] />

</Messages>
```

Subordinate tags may be used to define the word types that constitute a message type. For example, the word types that constitute “MyMessage” may be defined as follows:

```
15     <Message Name = “MyMessage” [message type settings]>

        <MessageWord WordName = “Word Type A”>
        <MessageWord WordName = “Word Type B”>
        <MessageWord WordName = “Word Type C”>
20

</Message>
```

Word types A, B, and C are the specific words that constitute “MyMessage,” and are preferably defined elsewhere in the bus file.

Message types, word types, and field types may each provide settings for further defining bus characteristics and behaviors. XML allows users to specify tag attributes. Bus files make use of these tag attributes to define the settings of the data types.

Message types provide “Variable Length” settings that allow users to specify whether a message consists of a fixed number of words or a variable number of words. For variable length messages, maximum and minimum length settings are also provided. Word types and field types may also provide variable length settings.

Users can establish various settings for field types. The following settings are provided in the preferred embodiment:

<b>Field Setting</b>	<b>Description</b>
Name	The name referenced during word-type definition and test definition.
Width	The field width specified in bit times. The field width can be variable.
Type	One of the “Field designations” from Table 1.
Transmit Order	A setting that determines if the MSB or the LSB is first.
Bit Stuffed	A Boolean that determines if bit stuffing applies to this field.
Include in Error Check	A Boolean that determines if this field should be included in error checking when the instrument calculates parity or CRC.
Special Symbol	If this field is of type special symbol, then the actual special symbol to be used is specified here.
Value	If this field is either of type constant data or constant non-data, then the actual value of the field is specified here.

Table 2. Field Settings

The use of communication element types, for defining message types, word types, and field types, provides users with a great deal of flexibility in structuring communication over a bus. Users can define fields for a bus, construct words out of specific fields, and construct messages out of specific words.

Given this flexibility, many opportunities arise for improving the quality of testing. For instance, users have broad abilities to perform fault injection in testing bus devices. Users can define field types, word types, and message types in ways that deliberately violate the protocol or specification of a bus. For testing purposes, a field can be defined as having too many bits or too few bits. A word can be defined as having too many fields or too few fields, or by having fields in the wrong locations within the word. Given the flexible, user-defined structure of messages, words, and fields, there are enormous possibilities for deviating from a bus protocol, in a controlled manner, to observe a device’s response.

This flexibility also enables users to create new bus models for new types of busses, including custom busses. Fig. 4 shows a process for creating a new bus model.

At step 410, a user examines the specification of the target bus. At steps 412 – 416, the user determines the specific field types, word types, and message types to be supported, based on the specification of the target bus and the user’s particular testing needs. At step 418, the user creates definitions for the desired field types, word types, and message types in a bus file for the target bus. The user then saves the bus file (step 418), where it can be accessed for interacting with the instrument.

Users need not generally create a new bus file from scratch each time one is needed. Different busses share many similar characteristics. Owing to the simplicity of the bus file (i.e., as an XML file), users can often create new bus files simply by copying existing ones and modifying a few settings.

The data types described herein, i.e., message types, word types, and field types, exist essentially as definitions within a bus file. These definitions can be brought into action for actually exercising a physical bus through the concept of “instances.” As is known, an instance is a specific expression of a particular type. A “message instance” is therefore a specific expression of a message type. Similarly, a “word instance” is a specific expression of a word type, and a “field instance” is a specific expression of a field type. These instances can be regarded more generally as “communication element instances.”

One may draw a parallel between the communication element types of a bus file and user defined data types provided in certain computer languages. For instance, the “C” computer language provides a “typedef” instruction for creating specific data types. Instances of a data type may be created in a computer program by declaring variables of that type. The computer program can then access and manipulate the instances of that type at runtime.

Communication element types of a bus file work much the same way. Users specify these types and can create instances of them to be used and manipulated in the context of a program. For example, computer software can be used to create an instance of MyMessage. The program can then manipulate the instance of MyMessage by establishing its settings, specifying its data, etc. The manipulated instance of MyMessage can then be transmitted or received for conducting the specific transfers defined by its words and fields.

Since message types are hierarchical constructs that include in their definitions constituent word types and field types, it is evident that “message instances” include not only instances of the messages themselves, but also instances of their constituent word

types and field types. In the preferred embodiment, the bus test instrument includes a software API (applications program interface) that allows users to create message instances. Each message instance has a software “handle” and is persisted in memory. The API can access the message instance via its handle to manipulate its data or execute the message instance.

Users preferably communicate with the API using function calls. In the preferred embodiment, the bus test instrument is a VXI instrument and the API is implemented with a VXI plug-and-play driver.

Two types of message instances can be created for message types: transmit message instances and expect message instances. Transmit message instances are used to send information over the bus. Expect message instances are used for receiving information over the bus. Expect message instances are similar to transmit message instances in that expect message instances also define the structure of blocks of information that appear on a bus or other communication medium. But while transmit message instances require users to provide the *data* to be transmitted, expect message instances require that the users specify only the *structure* of the expected data (e.g., word types and timing) and not the data itself. For testing purposes, however, one may specify expect data for expect message instances, i.e., data expected over the bus. Expect data can be compared with data actually received to determine whether expected results were obtained.

For both transmit and expect message instances, it is desirable to provide users with control over the timing of messages. Preferably, message type definitions found in a bus model contain default timing values. Message instances may either use or supercede those defaults. In the preferred embodiment, users may specify the following timing characteristics for message types or message instances:

- a delay to be enforced before the message instance can be transmitted, referred to as a premessage gap. Premessage gap definition includes the specification of the point of time from which the delay should be enforced, which includes end of last transmitted word, end of last received word, or any other event in the system.
- a delay to be enforced between the words of the message being transmitted, referred to as the preword gap

- a timeout for receiving the beginning of the expected message, referred to as the begin message timeout. Similar to the premessage gap this specification can include a flexible definition of the point of time when this time period starts.
- a timeout for receiving any word of the expected message, referred to as the word gap timeout.
- a period of time to check for to follow the expected message to guarantee that the message ended properly, referred to as the trailing gap.

Common timing defaults for the entire bus protocol, i.e. affecting multiple message types, can be provided as well. Such defaults include intermessage gap, interword gap, response time, no response timeout, no word timeout, as well as minimum and maximum values for any of these. Preferably, any of these defaults may be used for any of the message timing settings mentioned above.

Having described one embodiment, numerous alternative embodiments or variations can be made. For example, as disclosed above, reference is made to message types, word types, and field types. However, other communication element types may be used to represent additional layers of a communication protocol. For example, one may wish to implement a “transaction type,” which includes a group of message types. Therefore, the invention is not limited to the three communication element types disclosed.

In addition, some communication protocols do not define all the layers of the bus model. For instance, RS-232 does not define message types. The invention still applies to these busses, however, by supporting user-definable elements for other layers that the protocol does support. It should be understood, therefore, that the invention still applies where a bus does not support all the communication element types disclosed herein.

The concept of “busses” has a broad definition. Nevertheless, it is apparent from the foregoing that the user-definable communication element types can be applied to any communication medium, regardless of whether it is formally considered to be a “bus.” Therefore, the invention is not strictly limited to busses.

Moreover, the communication element types have been described herein as corresponding to specific layers of a generic bus model. But the invention is not limited to use with the particular bus model disclosed. Rather, the invention can be applied wherever a generic, layered model for communications can be described, regardless of its form.

The use of communication element types has been described in connection with bus testing. It is evident, however, that the invention applies in various contexts and is not limited to use with any particular instrument or with instruments in general. The concept of user-definable communication element types may be applied for simulating,  
5 emulating, or testing communications media. It may be used for communicating over a bus, for example via a general I/O circuit that can assume the protocol of any desired bus. It may also be used simply for representing or describing bus structure and behavior.

Therefore, while the invention has been particularly shown and described with reference to the preferred embodiments thereof, it will be understood by those skilled in  
10 the art that various changes in form and detail may be made therein without departing from the spirit and scope of the invention.